

# SURANGA D. HETTIARACHCHI

Assistant Professor  
Computer Science Department  
Indiana University Southeast  
4201, Grant Line Road  
New Albany, IN 47150  
Phone:(812)-941-2698  
Fax :(812)-941-2637

<http://ada.ius.edu/~suhettia/>

Email: [suhettia@ius.edu](mailto:suhettia@ius.edu)

## EDUCATION

**University of Wyoming**, Laramie WY  
Ph.D., Computer Science, September 2007  
Thesis - Distributed Evolution for Swarm Robotics  
Advisor - Dr. William M. Spears

**University of Wyoming**, Laramie WY  
M.S., Computer Science, December 2002

**University of Wyoming**, Laramie WY  
B.S., Management Information Systems, December 1999

**Australian Computer Society**, Complete Examination, June 1995.

**National Center for Computing**, United Kingdom  
Diploma in Computer Studies, December 1993

**IDM Computer Studies**, Colombo Sri Lanka  
Diploma in Advanced Programming Techniques Using COBOL, June 1993

**IDM Computer Studies**, Colombo Sri Lanka  
Diploma in Computer Studies, September 1992

## ACADEMIC AND INDUSTRY EXPERIENCE

*08/09–present* **Assistant Professor, Computer Science Department, Indiana University Southeast** , New Albany, IN

*09/07–07/09* **Visiting Assistant Professor, Computer Science and Multimedia Department, Eastern Oregon University** , La Grande, OR

*06/08–present : seasonal* **Consultant, Swarmotics LLC.** , Laramie, WY

*06/08–09/08* **Visiting Research Professor, Distributed Robotics Laboratory - University of Wyoming**, Laramie WY

Implemented fully distributed Physicomimetics algorithm on five Maxelbot robots, enhanced obstacle avoidance module (OAM) with extra sensors, and implemented a wireless data transfer module on Maxelbot. Supported by Eastern Oregon University summer faculty research grant.

**01/07–09/07 Research Assistant, Distributed Robotics Laboratory - University of Wyoming, Laramie WY**

Designing and implementing algorithms for obstacle avoidance module (OAM) that runs on a PIC micro-controller. Integrating OAM on real robotic architecture (MMP5) and testing in different obstacle courses. Funded by Joint Robotics Program, Office of the Secretary of Defense. PI: Dr. William Spears.

**02/00–12/06 Teaching Assistant, Computer Science Dept. - University of Wyoming, Laramie WY**

Teaching, grading, and preparing assignments for various computer science labs and summer courses.

**01/03–12/06 Research Assistant, Computer Science Dept. - University of Wyoming, Laramie WY**

Developed a fast learning system, called DAEDALUS (Distributed Agent Evolution with Dynamic Adaptation to Local Unexpected Scenarios), for goal-seeking robot swarms in dynamic environments. Empirically analyzed the feasibility of DAEDALUS for agents with obstructed perception. Investigated the behavior of agents that use the *artificial physics* framework of Drs. William and Diana Spears for navigating through obstacle fields.

**5/04–5/05 Research Assistant, Computer Science Dept. - University of Wyoming, Laramie WY**

Examined several potential energy models within the *artificial physics* framework, used to control aerial surveillance assets (such as UAVs) tasked with detecting ground-based targets (such as tanks and transport vehicles). Funded by DARPA. PI: Prof. William Spears.

**5/05–01/07 : seasonal Instructional Computing Services - University of Wyoming, Laramie WY**

Creating and Trouble shooting WebCT and eCompanion web courses for distance learning classes. Assisting instructors and students with web based course technology. Helping patrons with general computer technology.

**05/99–08/99 Intern, 3M, St.Paul, MN**

Set up the Trading Partner Project web page for sharing of models and project information. GUI prototype development for the CORBA API.

**12/99–05/01 Wyoming Cancer Control Network, Laramie, WY**

Set up and maintained a database. This project provided a way for health-care professionals to quickly and easily view cancer information and communicate among themselves about issues related to cancer and its treatments, using a searchable web page that provides "quick links" to other pre-screened web pages.

**02/94–07/96 IDM Computer Studies, Colombo, Sri Lanka**

Worked as a computer instructor and a supervisor for junior instructors. Lectured in various application languages and packages. Coordinated classes. Organized and maintained training programs for new instructors. Prepared employee work schedules and students' practical allocation reports. Maintained computer systems. Managed lab instructors' activities.

## COURSES TAUGHT AND CURRENTLY TEACHING

- Indiana University Southeast Courses
  - FYS-104 (Freshman Year Seminar, *Fall '12*) (*1 credit*)
  - CSCI-C 105 (Intro. to C Programming, *Summer '11*) (*3 credits*)
  - CSCI-C 202 (Intro. to Software Systems, *'09 through '14*) (*4 credits*)
  - CSCI-C 201 (Computer Programming II, *Spring '11, Summer '12, '13, '14*) (*4 credits*)
  - CSCI-C 335 (Computer Structures, *Fall '11*) (*4 credits*)
  - CSCI-C 311 (Programming Languages, *Fall '11, Spring '12*) (*4 credits*)
  - CSCI-C 458 (Intelligent Robots, *Spring '11, '13*) (*4 credits*)
  - CSCI-C 490 (Independent Studies, *Spring '11, Fall '14*) (*1 credit*)
- Eastern Oregon University Courses
  - CS 410-Special Topics (Robotic Research, *Spring'09*) (*variable credits*)
  - CS 311-Class (Operating Systems, *Spring'09*) (*3 credits*)
  - CS 162-Class (Foundations of CS II, *Spring'09*) (*4 credits*)
  - CS 260-Class (Data Structures, *Spring'09 and Spring'08*) (*4 credits*)
  - CS 360-Class (Object-Oriented Programming with C++, *Winter'09 and Winter'08*) (*4 credits*)
  - CS 161-Class (Foundations of CS I, *Winter'09*) (*4 credits*)
  - CS 248-Class (Unix Programming, *Winter'09 and Winter'08*) (*3 credits*)
  - CS 221-Class (C/C++ Programming, *Fall'08*) (*4 credits*)
  - CS 318-Class (Analysis of Algorithms, *Fall'08 and Fall'07*) (*4 credits*)
  - CS 410-Class (Robotics, *Spring'08*) (*4 credits*)
  - CS 140-Class (Microcomputer Systems, *Spring'08*) (*3 credits*)
  - CS 314-Class (Computer Architecture, *Winter'08*) (*4 credits*)
  - CS 210-Class (Multi-Agent Systems, *Fall'07*) (*4 credits*)
  - CS 301-Class (Assembly Language Programming, *Fall'07*) (*4 credits*)
- University of Wyoming Courses
  - COSC 3020-Labs (Analysis of Algorithms, *Fall'02 – Fall'06*) (*4 credits*)
  - COSC 2030-Labs (Computer Science II – *Fall'06*) (*4 credits*)
  - RESE 0064-Class (Robotics for High School Students (Upward Bound Program), *Summer '06*) (*6 credits*)
    - MBAM 5140-Class (Programming Techniques using JAVA (MBA Program), *Summer '04*) (*3 credits*)
    - RESE 0025-Class (MSW Logo and JAVA Web Start for High School Students (Upward Bound Program), *Summer '04*) (*4 credits*)
  - COSC 1030-Class and Labs (Problem Solving using C++, *Spring '00 – Summer '03*) (*4 credits*)
  - COSC 1010-Labs (Introduction to Programming using JAVA, *Spring'00 – Spring '02*) (*4 credits*)

## NEW COURSE DEVELOPMENT

- Indiana University Southeast Courses
  - CS 458 (Intelligent Robots, Indiana University Southeast, *Spring'11*) (*4 credits*)
- Eastern Oregon University Courses
  - CS 410-Class (Robotics, Eastern Oregon University, *Spring'08*) (*4 credits*)
  - CS 140-Class (Microcomputer Systems, Eastern Oregon University, *Spring'08*) (*3 credits*)
  - CS 210-Class (Multi-Agent Systems, Eastern Oregon University, *Fall'07*) (*4 credits*)

- University of Wyoming Courses
  - RESE 0064-Class (Robotics for High School Students (Upward Bound Program), University of Wyoming, *Summer'06*) (*6 credits*)
  - RESE 0025-Class (MSW Logo and JAVA Web Start for High School Students (Upward Bound Program), University of Wyoming, *Summer'04*) (*4 credits*)

## PRINCIPAL AREAS OF RESEARCH

- The control, design, and analysis of distributed adaptive robotic sensing networks
- Development of novel learning and adaptation algorithms for robotic swarms
- Autonomous robot architectures
- Evolutionary algorithms
- Neural networks
- Search algorithms and optimization problems

## PAPERS IN PREPARATION

Hettiarachchi, S. (2015). Using scouts to enhance heterogeneous learning.

Hettiarachchi, S. (2015b). Unsupervised swarm learning with sensor failure.

## REFEREED JOURNAL, CONFERENCE AND WORKSHOP PUBLICATIONS

Tyler, J. and S. Hettiarachchi (2015). A comparative analysis of three algorithms for uniform coverage. In *The Journal of Computing Science in Colleges*, Volume (To appear). Consortium for Computing Sciences in Colleges.

Kleczyński, S., M. Rayner, and S. Hettiarachchi (2014). Autonomous search and retrieval. In J. Meinke (Ed.), *The Journal of Computing Science in Colleges*, Volume 29-5, pp. 164–170. Consortium for Computing Sciences in Colleges.

Hettiarachchi, S. (2012). Physicomimetics for mobile robot obstacle avoidance. In *The 13th International Conference on Software Engineering, Artificial Intelligence, Networking and Parallel/Distributed Computing*, Volume 978-1-4673-2120-4, pp. 444–450. IEEE Computer Society.

Riddle, J., R. Hughes, N. Biefeld, and S. Hettiarachchi (2012). A user friendly software framework for mobile robot control. In S. Visa (Ed.), *The 23rd Midwest Artificial Intelligence and Cognitive Science Conference*, Volume 0074-841-4, pp. 44–49. CEUR.

Hettiarachchi, S. (2010). An evolutionary approach to swarm adaptation in dense environments. In *IEEE International Conference on Control, Automation and Systems*, pp. 962–966. IEEE Press.

Hettiarachchi, S. (2010b). Improving swarm survival using DAEDALUS. In D. Vrajitoru (Ed.), *The 21st Midwest Artificial Intelligence and Cognitive Science Conference*, pp. 36–43. Indiana University South Bend.

- Hettiarachchi, S. and W. Spears (2009). Distributed adaptive swarm for obstacle avoidance. In *International Journal of Intelligent Computing and Cybernetics*, Volume 2 No 4, pp. 644–671. Emerald Group Publishing.
- Hettiarachchi, S., P. Maxim, W. Spears, and D. Spears (2008). Connectivity of collaborative robots in partially observable domains. In *8th International Conference on Control, Automation and Systems (ICCAS 2008)*, pp. 721–728. IEEE Press.
- Maxim, P., S. Hettiarachchi, W. Spears, D. Spears, J. Hamann, T. Kunkel, and C. Speiser (2008). Trilateration localization for multi-robot teams. In *Proceedings of the International Conference on Informatics in Control, Automation and Robotics, Special Session on MultiAgent Robotic Systems*, pp. 301–307.
- Hettiarachchi, S., E. Cohen, T. Willey, and N. Schmidt (2008). Developing a mobile robot simulation as a research tool. In J. Meinke (Ed.), *The Journal of Computing Science in Colleges*, Volume 23-6, pp. 181–186. Consortium for Computing Sciences in Colleges.
- Hettiarachchi, S. and W. Spears (2006). DAEDALUS for agents with obstructed perception. In *SMCals/06 IEEE Mountain Workshop on Adaptive and Learning Systems*, pp. 195–200. IEEE Press, Best Paper Award.
- Hettiarachchi, S. (2006). Distributed online evolution for swarm robotics. In T. Ishida and A. B. Hassine (Eds.), *Autonomous Agents and Multi Agent Systems*, pp. 17–18. Doctoral Mentoring Program.
- Hettiarachchi, S., W. Spears, W. Kerr, D. Zarzhitsky, and D. Green (2006). Distributed agent evolution with dynamic adaptation to local unexpected scenarios. In *Second GSFC/IEEE Workshop on Radical Agent Concepts*. Springer.
- Hettiarachchi, S. and W. Spears (2005). Moving swarm formations through obstacle fields. In *International Conference on Artificial Intelligence*, Volume 1, pp. 97–103. CSREA Press.
- Spears, W., D. Zarzhitsky, S. Hettiarachchi, and W. Kerr (2005, invited). Strategies for multi-asset surveillance. In *IEEE Networking, Sensing and Control*, pp. 929–934. IEEE Press.
- Spears, W., D. Spears, R. Heil, W. Kerr, and S. Hettiarachchi (2005). An overview of physicomimetics. In E. Sahin and W. Spears (Eds.), *Lecture Notes in Computer Science State-of-the-Art Series*, Volume 3342, pp. 84–97. Springer.

## BOOK CHAPTERS

- Hettiarachchi, S., P. Maxim, and W. Spears (2008). An architecture for adaptive swarms. In X. P. Gu (Ed.), *Robotics Research Trends*. Nova Publishers.
- Hettiarachchi, S. (2011). Adaptive learning of robot swarms in unfamiliar environments. In W. M. Spears and D. F. Spears (Eds.), *Physicomimetics: Physics-Based Swarm Intelligence*. Springer.

## FUNDING

- Indiana University Southeast, undergraduate grant-in-aid of research of \$964 to support student research, *Fall '13*.
- Indiana University Southeast online training cohort grant of \$1000 *Fall '13*.
- Indiana University Southeast, undergraduate student research assistant program grant of \$1000 to support a student assistant, *Fall '12*.
- IU Overseas Conference Grant of \$750 and IU Southeast travel grant of \$400 to attend ICCAS 2010.
- IU Southeast travel grant of \$600 to attend Midwest Artificial Intelligence and Cognitive Science Conference, 2010.
- Indiana University Southeast, undergraduate student research assistant program grant of \$1000 to support a student assistant, *Spring '10*.
- Indiana University Southeast, summer faculty research fellowship grant of \$8000, *Summer '10*.
- Indiana University Southeast, faculty research support program grant of \$1000 to support a student assistant, *Fall '09*.
- Indiana University Southeast faculty research start-up grant of \$20,000 to start Department of Computer Science Distributed Robotics Laboratory, *Fall '09*.
- Oregon University System - Eastern Oregon University travel grant of \$1000 for “Robotics - Hands-On and Interactive” program presented by Johns Hopkins University Center for Talented Youth and Oregon University System, OR, *Spring '09*.
- Eastern Oregon University faculty summer research grant of \$12,000 for swarm robotics research titled “Distributed Communication Architecture for Robot Swarms” at University of Wyoming Distributed Robotics laboratory, *Summer '08*.
- Eastern Oregon University-Engineering and Technology Industry Council of Oregon funding of \$15,000 for undergraduate robotics research, *Fall '07 - Spring '09*.
- Eastern Oregon University faculty development fund travel grant of \$1300 to present research work at CCSC08, CA, *Spring '08*.
- University of Wyoming travel grant of \$3000 to present research work at AAMAS06 and ISWA, Japan, *Spring '06*.
- University of Wyoming travel grant of \$2000 to present research work at three conferences, *Spring and Fall '05*.

## FUNDING PROPOSALS

- The National Science Foundation grant proposal titled “IU Southeast Computational Scholars Program” with John Doyle, Ron Finkbine, Chris Kimmer (Co-PIs), and Suranga Hettiarachchi (PI) (2014-pending).
- The National Science Foundation grant proposal titled “Improving Retention in Computational Sciences through Student Support, Student Engagement and Curriculum Enhancement ” with Hossein Hakimzadeh(PI), Awny Alnusair, Bhaskara Kopparty, April Savoy, and Suranga Hettiarachchi (Co-PIs) (2014 - denied).
- The National Science Foundation grant proposal titled “CER: make.edu : Using makerspaces to teach computing at universities” with Christopher Kimmer (PI), John Doyl and Gary Pinkston (Co-PI), Suranga Hettiarachchi (Senior Personnel) ( 2013 - denied)
- Indiana University Southeast, undergraduate grant-in-aid proposal titled “Learning by Doing-Autonomous Mapping with Ground and Aerial Robots” (2013), (funded).

- The National Science Foundation grant proposal titled "GEAR: Goals for Enrollment And Retention" with April Savoy (PI), Awny Alnusair, Bhaskara Kopparty, Hossein Hakimzadeh, and Suranga Hettiarachchi (Co-PIs) (2012 -declined).
- Indiana University Southeast, undergraduate research assistant grant proposal titled "Exploration of Disaster Sites using Autonomous Mobile Robot Swarms" (2012), (funded).
- Partnering Synopsis for NASA Langley Research Center in response to Solicitation Number: SS-ROBOTIC-SWARMS with Sanza T. Kasadi, Paul M. Maxim, Diana F. Spears, William M. Spears, and Dimitri Zarzhitsky (2011 - declined).
- The National Science Foundation grant proposal titled "RET in Engineering and Computer Science Site - Knowledge Transfer from Teachers to Students Through Robotic Research and Competition" with John Doyle and Gary Pinkston (Co-PIs) (2011 - declined).
- Grant proposal titled "Strengthening Scientific Education Through Robotics" submitted to The Horseshoe Foundation of Floyd County (2011 - declined).
- Indiana University Southeast, undergraduate research assistant grant proposal titled "Implement an Obstacle Avoidance Algorithm for X80Pro Robots" (2010), (funded).
- Indiana University Southeast, summer faculty fellowships for research proposal titled "Implementation of a Fully Distributed Control Algorithm on X80Pro Robots" (2009), (funded).
- Indiana University Southeast, faculty research support program grant proposal titled "Funding Request to Implement an Intelligent Robot Localization Technique for X80Pro Robots" (2009), (partially funded).
- Collaborator "Advancing a Physics-Based Control Framework for Distributed Agents", Submitted to Office of Naval Research, Co-Principal Investigators: Lee Frey, Harbor Branch Oceanographic Institution. Dr. Paul Wiegand III, Florida Atlantic University. Dr. William M. Spears, Swarmotics LLC. (2009) (declined).
- Eastern Oregon University, summer research grant proposal titled "Distributed Communication Architecture for Robot Swarms" in collaboration with University of Wyoming Distributed Robotics laboratory (funded) (2008).
- Principal Investigator: A Novel Approach for Early Detection of Forest Fire. White paper submitted to Union county, Forest Service (declined).
- Principal Investigator: DARPA Small Business Initiative Research Program "Artificial Physics-based Cooperative Behavior in Fluidic Environments". Co-Principal Investigators: Dr. Kent Henry, ADA Technologies. Professors William and Diana Spears, University of Wyoming. (2007) (declined).
- Principal Investigator: DARPA Small Business Initiative Research Program "Cooperative Robot/Human Teams for Assessing Chemical Threats". Co-Principal Investigators: Dr. Kent Henry, ADA Technologies. Professors William and Diana Spears, University of Wyoming. (2007) (declined).

## DOCTORAL AND MASTERS THESES

Hettiarachchi, S. (2007). *Distributed Evolution for Swarm Robotics*. Ph. D. thesis, University of Wyoming.

Hettiarachchi, S. (2002). Using data-marts to create an internet-based system for gathering information. Master's thesis, University of Wyoming.

## HONORS AND RECOGNITION

- Nominated by students for Indiana University Southeast Distinguished Teaching Award in 2013, 2012, 2011 and 2010

- Faculty Honoree of IUS Authors and Artists, 2012, 2011, 2010
- Program Committee Membership Diploma for outstanding contributions to ICINCO 2011, 2010.
- Invited chair of the Mobile Robots and Navigation session at ICCAS 2010
- University of Wyoming Graduate School Honors, 2007: Oral Presentation Winner (with Paul Maxim)
- Best Paper Award: 2006 IEEE Mountain Workshop on Adaptive and Learning Systems
- Presenter among 24 selected doctoral students out of 96 applicants: 2006 Doctoral Mentoring Program, AAMAS
- Dean's Honor Roll: 1996, 1997 University of Wyoming, College of Arts and Sciences
- International Student Scholarship: 1997, 1999, 2002, 2003, 2006 University of Wyoming
- Dunnawald Memorial Scholarship: 1998, 2004, 2005 University of Wyoming

## PRESENTATIONS/PARTICIPATION

- Presenter at ACM SIGCSE 2014 Special Session: Engaging Mathematical Reasoning Exercises. Topic "Simple Mathematical Simulations for Event Driven Programming," Atlanta, Georgia. (March 2014).
- Presenter at Eastern Kentucky University Research Symposium. Topic: "Physics-based swarm intelligence" , Richmond, Kentucky, USA. (March 2013).
- Panellist of the Georgia Undergraduate Research Conference Workshop on Student Research, Columbus State University, Columbus, Georgia, USA. (February 2013).
- Panellist of the Indiana University Southeast Workshop on Student Research, New Albany, Indiana, USA, 2012.
- The 23rd Midwest Artificial Intelligence and Cognitive Science Conference, University of Cincinnati, Ohio, USA, 2012.
- Swarm adaptation in dense environments: IEEE/ICROS - International Conference on Control, Automation and Systems - Seoul, Korea (2010).
- Autonomous Distributed Control of X80Pro Robots. IU Southeast SARC Series, New Albany, Indiana, 2010.
- The 21st Midwest Artificial Intelligence and Cognitive Science Conference, Indiana University-South Bend, 2010.
- Lunch time talk series, Indiana University Southeast- Institute for Learning & Teaching Excellence, 2009.
- Spring Colloquium, Eastern Oregon University, La Grande, Oregon, USA, 2008.
- First Annual Consortium for Computing Sciences in Colleges - Southwestern Regional Conference California State University - Northridge, California, USA, 2008.
- Textron Corporation, at University of Wyoming, Laramie, Wyoming, USA, 2008.
- Fifth Graduate Student Symposium at University of Wyoming, Laramie, Wyoming, USA, 2006.
- IEEE Mountain Workshop on Adaptive and Learning Systems, Utah State University, Logan, Utah, USA, 2006.
- Doctoral Mentoring Program, Future University of Hakodate, Japan, AAMAS, 2006.
- International Students Workshop on Agents, Kyoto University, Japan, 2006.
- Fourth Graduate Student Symposium at University of Wyoming, Laramie, Wyoming, USA, 2006.
- International Conference on Artificial Intelligence, Las Vegas, Nevada, USA, 2005.
- Second GSFC/IEEE Workshop on Radical Agent Concepts, NASA Goddard Space Flight Center, Washington D.C., USA, 2005.
- IEEE International Conference on Networking, Sensing and Control, Tucson, Arizona, USA, 2005.
- Third Graduate Student Symposium at University of Wyoming, Laramie, Wyoming, USA, 2005.



- Second Graduate Student Symposium at University of Wyoming, Laramie, Wyoming, USA, 2004.

## STUDENTS SUPERVISED AND UNDER SUPERVISION

### Past and Present Undergraduate Projects

- Ryan Compton, Adam Striegel, and Kuan-Yi Wu : Toxic Gas Warning Robot: Robotics with Practical Application, Presented at 2015 - 11th Annual IU Southeast Student Conference. Best Oral Presentation.
- Harry Lane, Bryan Forbis, and Cory Hurst : Robot for Environmental Mapping and Localization, Presented at 2015 - 11th Annual IU Southeast Student Conference.
- Stephanie Hatton, Shawn Pixley, and James Warth: Autonomous Flame-Detecting Robot, Presented at 2015 - 11th Annual IU Southeast Student Conference.
- Nolan Pruett, Ryan Webb, and Erica Wright: Security Robot for Perimeter Defense, Presented at 2015 - 11th Annual IU Southeast Student Conference.
- William Reilly: Neural Network for Handwritten Digit Recognition, Presented at 2015 - 11th Annual IU Southeast Student Conference.
- Computer Science Hackerspace Student Group: Learning by Doing - Autonomous Mapping Using Ground and Aerial Robots, 2013-2014. Partial work to be presented at 2015 Annual IU Southeast Student Conference.
- Adam Streigle and Nolan Pruett: Efficient Distributed Algorithm for a Batch Spell Checker in a Supercomputer, 2014-2015. Partial work to be presented at 2015 Annual IU Southeast Student Conference.
- Sage Kleczynski and Matthew Rayner: Autonomous search and retrieval using X80Pro robot. *Spring'13* Published in the The ACM Journal of Computing Sciences in Colleges 2014.
- Jeramey Tyler, Richard Garuccio, Alan Laffoon: Autonomous Navigation and Mapping of Unknown Environment. Best Oral Presentation - 2013, 9th Annual IU Southeast Student Conference. *Spring'13*
- Andrei Escartin, Erik George, Austin Hall: An Implementation of Marco Polo Using Heuristic Profiling on Autonomous Mobile Robots - Presented at the 9th Annual IU Southeast Student Conference. *Spring'13*
- Jeramey Tyler: Physicomimetics Navigation using Pyroelectric Sensors for Search and Rescue, *Summer and Fall'12*. Presented at 2013 Georgia Undergraduate Research Conference.
- Reuben Borrego, Scott Reinhardt, and Jesse Riddle: Using AP-Lite to Implement Pac-Man Game, *Spring'11*.
- Randall Heidorn, Greg Reinhardt, Nathaniel Biefeld, and Ryan Hughes: Distinguishing and Characterizing Objects in An Environment Through Sensor Modalities Using Bayesian Methods, *Spring'11*.
- Colton Jenkins: Adaptive mine sweepers in dynamic environments, *Spring'11*.
- Nicholas Phillips: Design and implement adaptive solutions based on evolutionary and neural network approaches for digit recognition problem, (B.S. in CS, *Spring'11*).
- Jesse Riddle: Implementing AP-lite control algorithm on X80-Pro autonomous mobile robot, *Fall'10*.
- Brian Wimpsett: A project titled "Predictability of Swarm Distribution in Partially Observable Environments" The project analyzes and predicts the required degree of distribution of a swarm in partially observable environments for effective navigation, *Fall'10*.
- Michael Francis: A project titled "Real-Time Robotic Sound Localization Using Parallel Processing with CUDA" The project try to improve the efficiency of sound localization using CUDA and

GPU, *Spring'10*.

- Jesse Riddle and Michael Revel: Research assistants at Indiana University Southeast, Robotics Laboratory. Assisting day to day activities of the laboratory and implementing a robot localization and obstacle avoidance algorithms for X80Pro robots, *Fall'09–Spring'10* .
- Brad Baker: Capstone Project Advisor (B.S. in CS, *Spring'09*). Implement a simulated dynamic mapping tool for hot-spot detection using a swarm of Physicomimetics driven unmanned aerial vehicles. Currently a MS student at Boise State University, ID.
- Eli Cohen, Tim Willey, Brad Nelson, Brad Baker, Cody Jarrett, and Nathan Schmidt: Fall'07 - current, undergraduate robotic research project. Addresses issues and techniques related to localization, data communication, obstacle avoidance by robot teams, and design and implement these techniques using physical robots.
- Nathan Schmidt: Capstone Project Advisor (B.S. in CS, *Spring'08*). Implement a novel hybrid neuro-evolution technique for digit recognition problem. Currently a MS student at Boise State University, ID.

#### OTHER PROJECTS COMPLETED

- Evolving Neural Networks for Digit Recognition
- Parameter Optimization using a genetic algorithm for goal seeking physics-based multi-agents in an obstacle course
- Optimizing interaction potentials for multi-asset surveillance
- Search problems and search techniques
- The performance of artificial neural networks in the keep-away RoboCup test-bed
- Chemical plume detection using neuro-evolution
- Implementation of a subset of the UNIX file system
- UW ticket Master Database
- Desktop Medical Assistant System

#### PROFESSIONAL SOCIETY MEMBERSHIPS

- IEEE
- Consortium for Computing Sciences in Colleges

#### CONFERENCE ACTIVITIES

- Advisory Board Member: The 25th Modern Artificial Intelligence and Cognitive Science Conference (MAICS 2014), Gonzaga University, Spokane, WA, USA (April 2014).
- Conference Co-Chair: The 24th Midwest Artificial Intelligence and Cognitive Science Conference (MAICS 2013), New Albany, Indiana, USA (April 2013).
- Program Committee Member: The 10th International Conference on Informatics in Control Automation and Robotics (ICINCO 2013), Reykjavik, Iceland (July 2013).
- Program Committee Member: The 12th IEEE/ACIS International Conference on Computer and Information Science (ICIS 2013) Toki Messe, Niigata, Japan (June 2013).
- Program Committee Member: The 14th International Conference on Software Engineering, Artificial Intelligence, Networking and Parallel/Distributed Computing (SNPD 2013), Kyoto, Japan (Aug 2013).
- Program Committee Member: The 23<sup>rd</sup> Midwest Artificial Intelligence and Cognitive Science Conference at University of Cincinnati, Cincinnati, OH, USA (April 2012).

- Program Committee Member: The 9<sup>th</sup> International Conference on Informatics in Control, Automation and Robotics (ICINCO 2012), Rome, Italy (July 2012).
- Program Committee Member: The 13<sup>th</sup> International Conference on Software Engineering, Artificial Intelligence, Networking and Parallel/Distributed Computing, Kyoto, Japan (Aug 2012).
- Program Committee Member: The 11<sup>th</sup> IEEE/ACIS International Conference on Computer and Information Science, Shanghai, China (May 2012).
- Program Committee Member: The 9<sup>th</sup> International Conference on Software Engineering Research, Management and Applications (SERA2012), Kunming, China (April 2012).
- Program Committee Member: 1<sup>st</sup> ACIS International Symposium on Software and Network Engineering, Seoul National University, Seoul, Korea (Dec 2011).
- Program Committee Member: The 8<sup>th</sup> International Conference on Informatics in Control, Automation and Robotics (ICINCO 2011), Noordwijkerhout, The Netherlands (2011).
- Program Committee Member: The 9<sup>th</sup> International Conference on Software Engineering Research, Management and Applications (SERA2011), Baltimore, USA (2011).
- Program Committee Member: The 12<sup>th</sup> International Conference on Software Engineering, Artificial Intelligence, Networking and Parallel/Distributed Computing (SNPD 2011), Sydney, Australia (2011).
- Program Committee Member: The 22<sup>nd</sup> Midwest Artificial Intelligence and Cognitive Science Conference (MAICS 2011), Cincinnati, USA (2011).
- Paper Reviewer: IEEE/ICROS - International Conference on Control, Automation and Systems - Seoul, Korea (2010).
- Program Committee Member: 7<sup>th</sup> International Conference on Informatics in Control, Automation and Robotics, Madeira, Portugal (2010).
- Paper Reviewer: IEEE Congress on Evolutionary Computation, Barcelona, Spain (2010).
- Paper Reviewer: Third Annual Consortium for Computing Sciences in Colleges - Southwestern Regional Conference, California Lutheran University, California, USA (2010).
- Program Committee Member: 8<sup>th</sup> ACIS-International Conference on Software Engineering Research, Management and Applications - Montreal, Canada (2010).
- Program Committee Member: 21<sup>st</sup> Midwest Artificial Intelligence and Cognitive Science Conference at IU- South Bend, Indiana, USA (2010).
- Program Committee Member: 7<sup>th</sup> ACIS -International Conference on Software Engineering Research, Management and Applications - Haikou, Hainan Island, China (2009).
- Paper Reviewer: IEEE International Conference on Evolutionary Computation, Special Session on “Techniques for Online and Distributed Evolutionary Computation” - Trondheim, Norway (2009).
- Paper Reviewer: IEEE/ICROS - International Conference on Control, Automation and Systems - Seoul, Korea (2008).
- Paper Reviewer: First Annual Consortium for Computing Sciences in Colleges - Southwestern Regional Conference, California State University - Northridge, California (2008).

## JOURNAL SERVICES

- Reviewer: Applied Swarm Intelligence, Springer. 2009.
- Editorial Board: Journal of Advanced Research in Evolutionary Algorithms (JAREA), 2008 – 2011.
- Co-organizer: Special Issue on Swarm Robotics for the International Journal of Intelligent Computing and Cybernetics (with William M. Spears, 2009).

## OTHER ACTIVITIES

- Coach of the 4th place winning team of ACM Mid-Central USA Programming Contest at University of Louisville (2013)
- 3rd place Winner of the UW International Week Photo Contest (2006)
- Robotics demonstrations/talks for UW child care school (2006)
- Robotics demonstrations/talks for Casper school system (2006)
- Presentation to Laramie Junior High School students on Sri Lankan geography and culture (2006)
- Robotics demonstrations/talks for UW Alumni (2005)
- Presentations to incoming undergraduate Engineering students on swarm robotics research
- President, International Student's Association, University Of Wyoming(1998/1999)
- Ex-Officio, Associated Students Of University of Wyoming (1998/1999)

### UNIVERSITY SERVICES

- Faculty advisor of IU Southeast ACM student chapter and Hackerspace (since '13).
- Senator of IU Southeast Faculty Senate ('13-'15).
- Member of the Suspension Appeals Committee at IU Southeast ('12, '13).
- Member of the Honors Council at IU Southeast ('10-'11, '13-'14).
- Member of the Satisfactory Academic Progress Committee at IU Southeast ('10,'11,'12, '13).
- Member of the Campus Emergency Notification Task Force at IU Southeast ('11, '12).
- IU Southeast 7<sup>th</sup> Annual Student Conference and Showcase judge (Spring 2011).
- Member of the IU Southeast Strategic Planning Goals Task Force (Fall '10).
- School of Natural Sciences representative and facilitator to IU Southeast academic honors convocation (Spring'10).
- Computer Science Department faculty representative to IU Southeast open house (Fall'09 and Spring'10).
- Organized NAO- Humanoid Robot presentation by Natanel Dukan at IU Southeast (Fall'09)
- Robotic workshops for incoming freshman class at Eastern Oregon University (2009)
- Conduct workshops for "Robotics - Hands - On and Interactive" program presented by Johns Hopkins University Center for Talented Youth and Oregon University System (2009)
- Conduct Robotic workshop for 4H students in "College Life" day at Eastern Oregon University (03/2009)
- Member of the Eastern Oregon University faculty scholar stipend proposals review committee (2008)
- Member of the judging panel of the INTEL-Oregon first LEGO league local tournament (2007, 2008)
- Member of the Cyber Initiatives committee (2007)
- Member of the Graduate School Panel for the students seeking graduate school admission (2007)